

System Study of a 60 GHz Wireless-Powered Monolithic Sensor System

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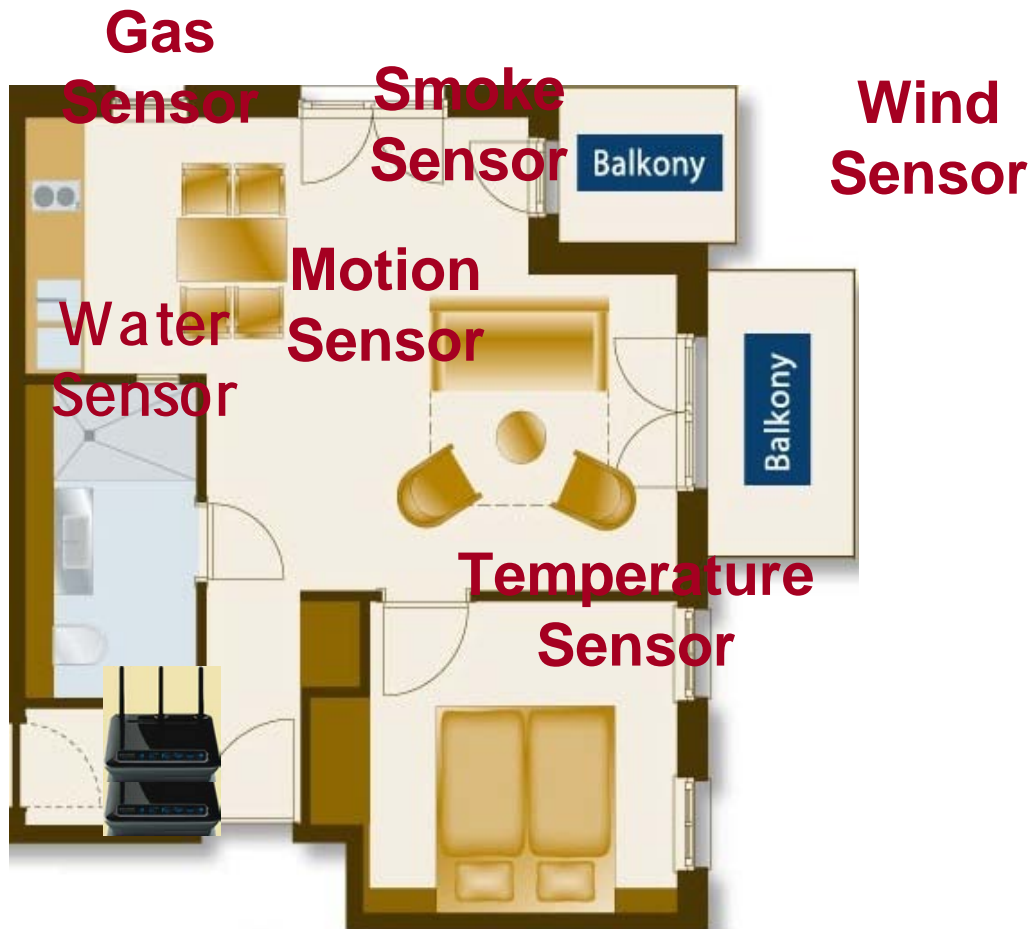


Where innovation starts

Outline

- **Motivation**
 - **Wireless-Powered**
 - **Monolithic**
 - **60 GHz**
- **System Overview**
- **System-Level Energy Budget Calculation**
 - **Comparison with a 2.4 GHz RFID system**
- **Conclusions**

Sensors are Going Wireless



Battery-Operated Wireless Sensors

Advantage:

- Easy deployment
- Lifetime of many years

Disadvantage:

- Limited life time
- Battery replacement
- Big Size
- Relative higher cost

Wireless-Powered Wireless Sensors

- **Self-Powered sensors using energy harvesting**
 - Vibration/Motion
 - Temperature difference
 - Light
 - Pressure
 - RF
 - ...



Wireless-Powered Wireless Sensors

- **Self-Powered sensors using energy harvesting**

- Vibration/Motion
- Temperature difference
- Light
- Pressure
- RF
- ...

Energy Harvesting using RF (i.e. Wireless-Powered) is a natural choice for Wireless Sensors.



Monolithic

- **Current energy scavenging sensors implement sensing and energy scavenging in two separate modules:**
 - **Larger size and higher price;**
 - **Not robust in harsh environments or on moving objects.**

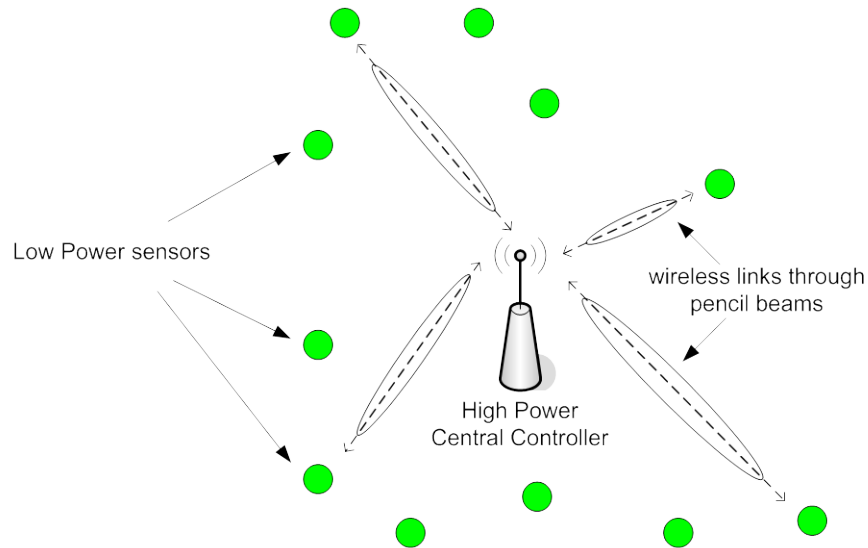
Monolithic

- **Current energy scavenging sensors implement sensing and energy scavenging in two separate modules:**
 - **Larger size and higher price;**
 - **Not robust in harsh environments or on moving objects.**
- **Monolithic sensor nodes:**
 - **On-chip energy harvesting, sensing and transceiving**
 - **Ultra low power TxRx**
 - **Small size (mm²)**

60 GHz

- **Small wavelength (5mm), possible to**
 - Integrate antenna on-chip,
 - Create large antenna arrays to
 - provide high antenna gain,
 - Create highly directional pencil beams.
- **Wide bandwidth available at 60 GHz enables**
 - High data rate in the order of Gbits/s,
 - short transmission burst.

60 GHz Wireless-Powered Monolithic Sensor System



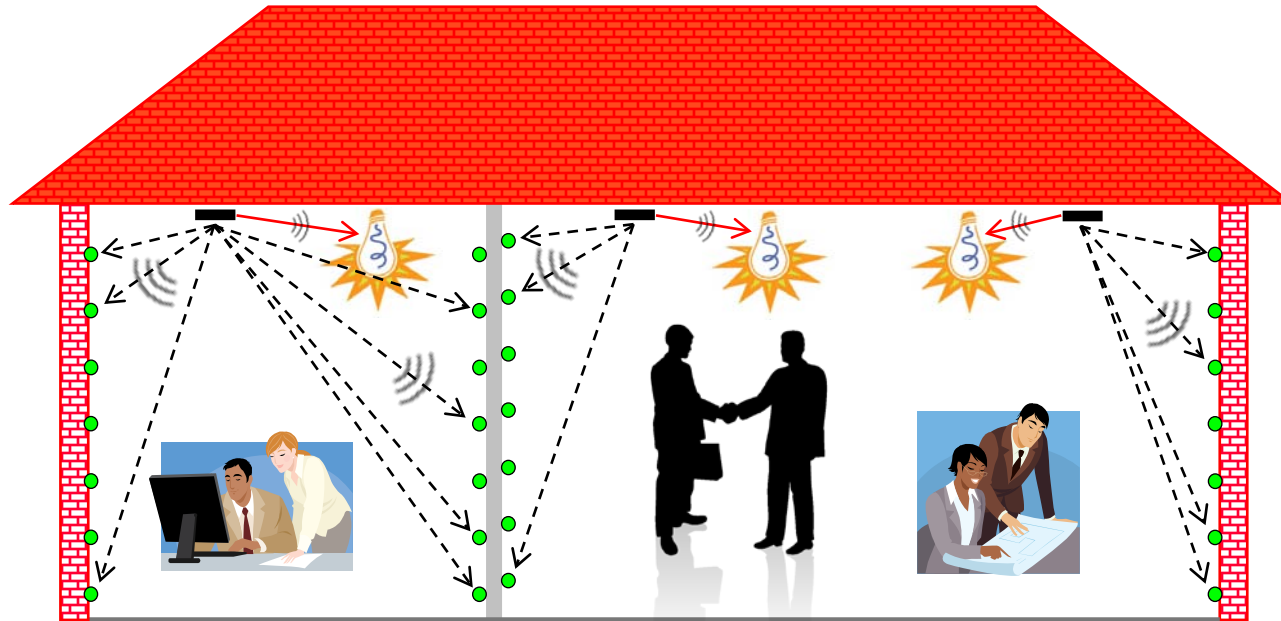
- Fully integrated sensor nodes with on-chip sensing, antenna, transceiver and energy scavenging.
- Central controller wirelessly transmits data and energy to sensor nodes.

A typical sensing cycle

1. Downlink: central controller sends energy and data to a sensor;
2. Uplink: the sensor sends required info. back to central controller.

• Work in ongoing in the STW project “PREMISS” (Power Reduced Monolithic Sensor System).

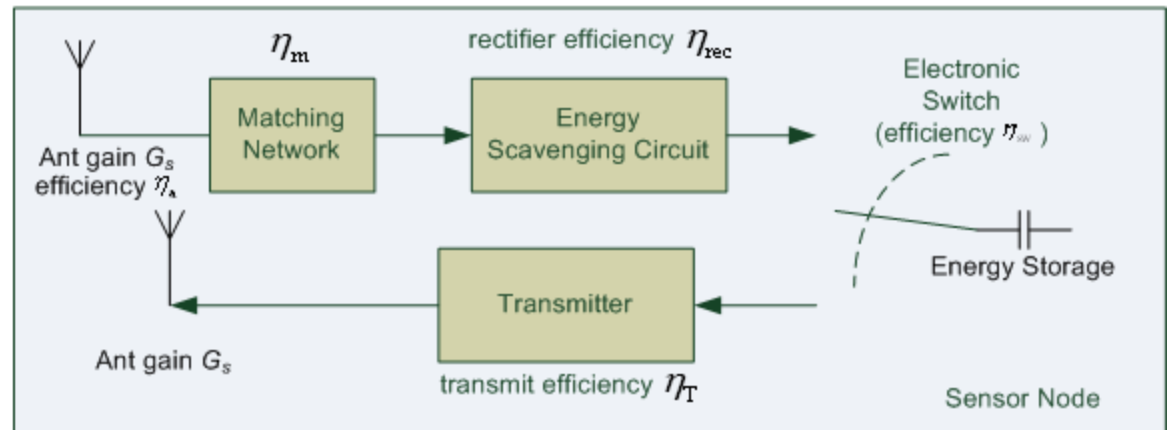
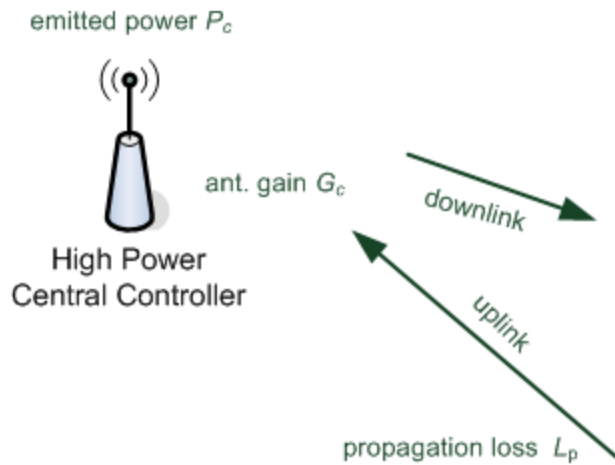
Possible Applications



Smart Wall

- Temperature measurement
- Proximity sensing (used for e.g. lighting control)
- Presence detection and tracking
- Activity monitoring

System Architecture



Central Controller Antenna gain and Path Loss

- At the central controller, the antenna gain

$$G_c = 10 \times \log_{10}(N_a)$$

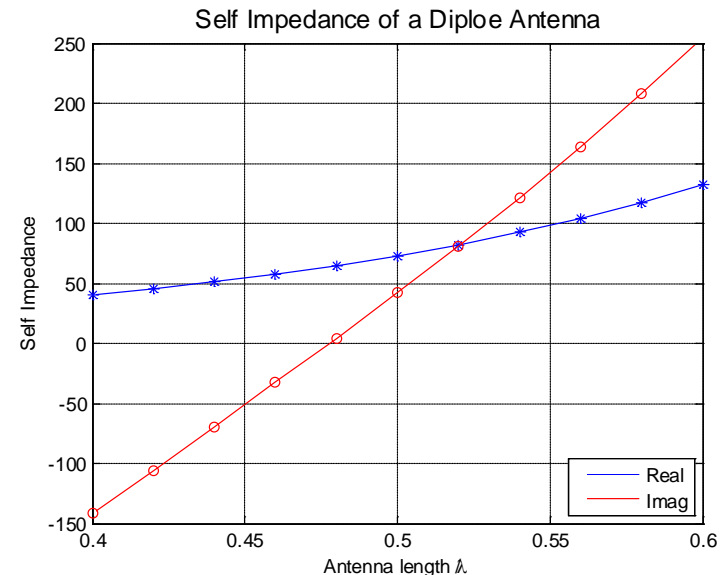
- Free space propagation loss

$$L_P = \left(\frac{4\pi d}{\lambda} \right)^2 = \left(\frac{4\pi df}{c} \right)^2$$

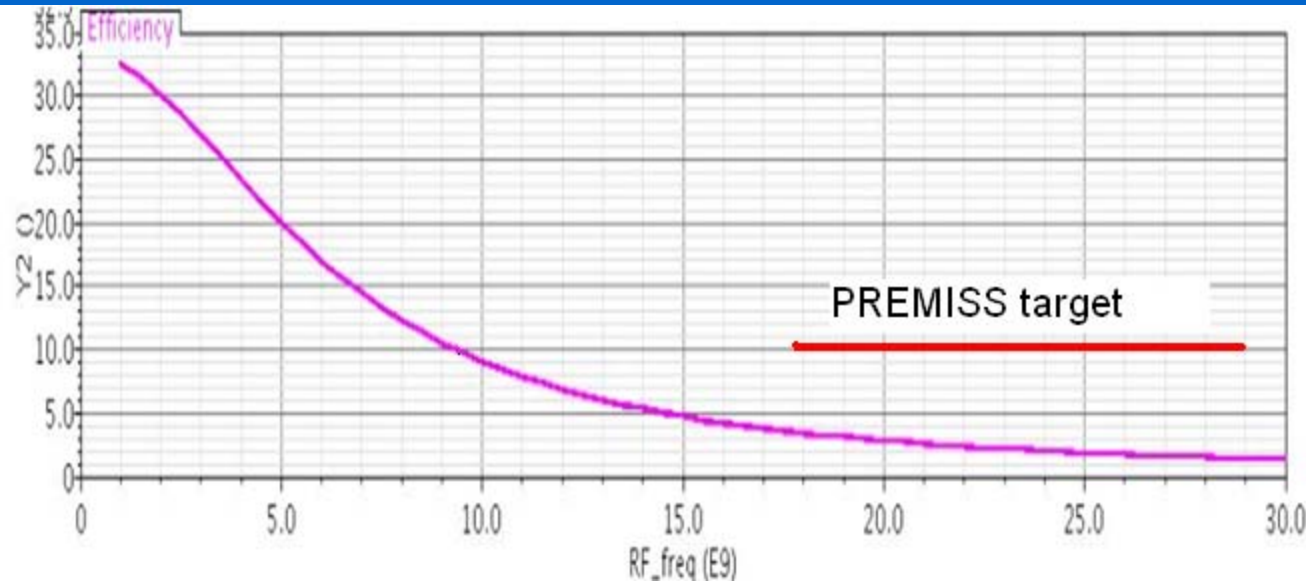
Sensor antenna related considerations

- At 60 GHz, integration of antenna on chip is possible.
- Due to lossy substrate, the antenna efficiency is lower.

• Due to small chip size (e.g. 1 mm^2 for the PREMISS project), the antenna impedance becomes more capacitive and results in more loss on the matching network.



Rectifier Efficiency



- The rectifier efficiency is heavily dependent on the frequency.
- At 2.4 GHz, 31% was achievable using 65 nm CMOS technology at an input power level of -19 dBm.
- For 60 GHz applications, the efficiency drops to 2% using state-of-the-art design.
- We project an improvement to about 10% for 60 GHz systems.

Loss on Electronic Switch and Capacitor Leakage.

- **An electronic switch is required to switch the energy storage capacitor between charging and discharging mode.**
- **The efficiency of this switch can be assumed 90%.**
- **For the application considered in PREMIS, the energy stored is immediately used for transmission. Hence energy leakage is negligible.**

Downlink Energy Budget

- The available power at the capacitor

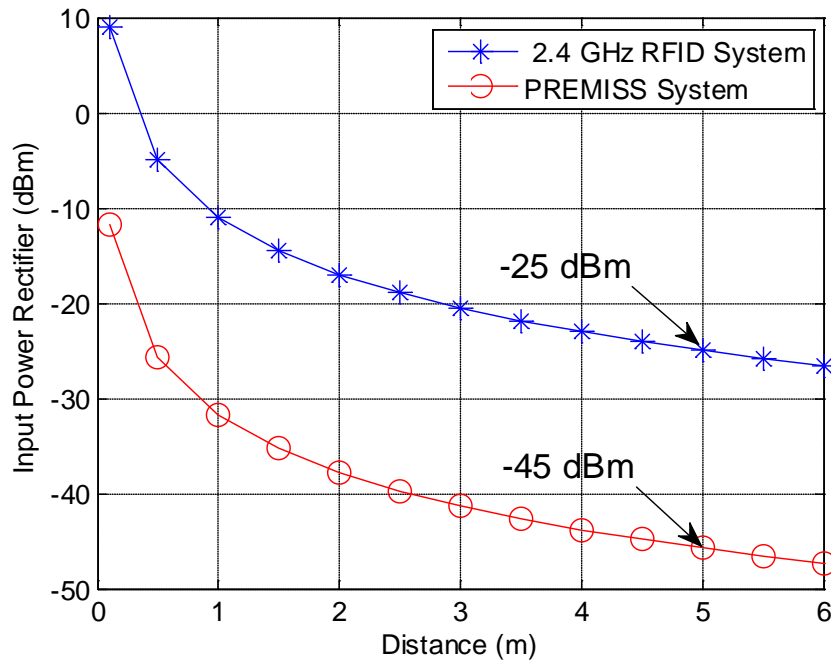
$$P_s = \frac{P_e G_c G_s}{L_p} \eta_a \eta_m \eta_{sw} \eta_{rec}$$

- We compare the PREMIS system with a typical 2.4 GHz RFID system

Parameters	PREMISS	2.4 GHz RFID
λ (mm)	5	125
P_e (dBm)	20	20
G_T (dB)	20	11
G_s (dB)	0	0
η_a	0.6	0.9
η_m	0.7	0.75×0.95
η_{sw}	0.9	0.9

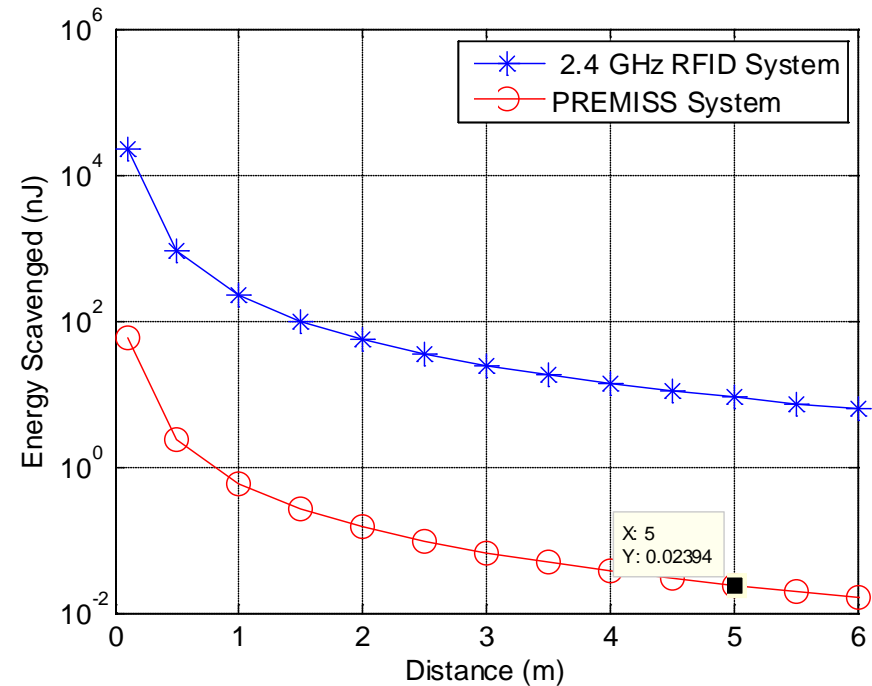
Downlink Energy Budget

Power available at Rectifier Input



Key-challenge: achieve a decent rectifier efficiency with low input power.

Energy harvested in 10 ms



Uplink transmission has to be very efficient.

Uplink Energy Budget

- The received signal power in the central controller

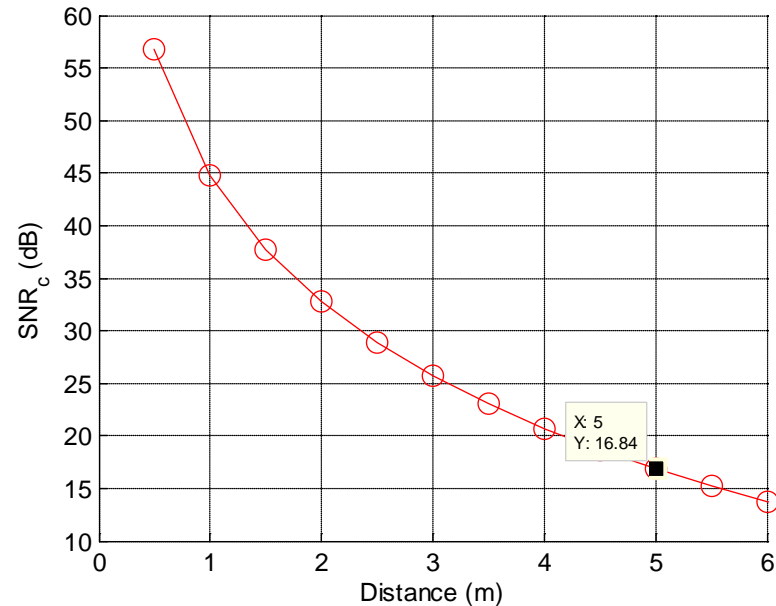
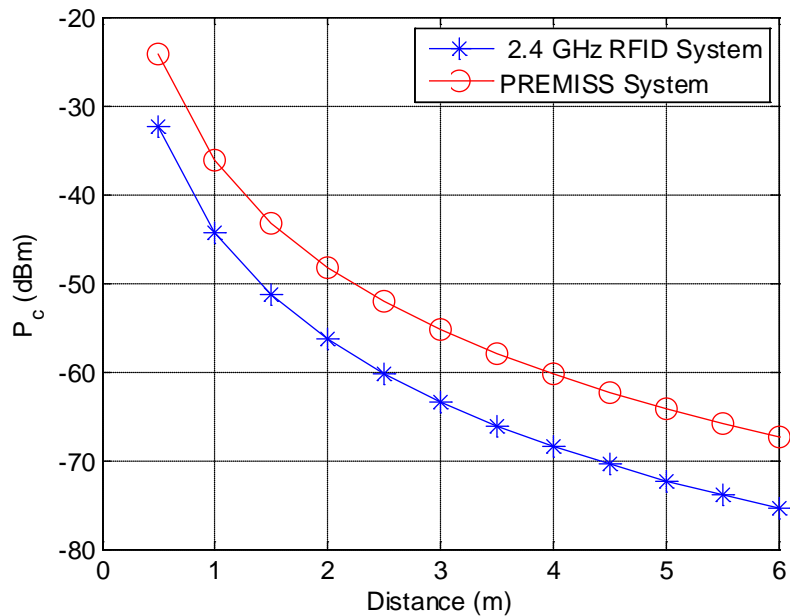
$$P_c = \frac{E_s}{t_d} \frac{G_s G_c}{L_p} \eta_T,$$
$$= \left(\frac{t_s}{t_d} \right) \left(\frac{P_e G_c^2 G_s^2}{L_p^2} \right) (\eta_a \eta_m \eta_{\text{rec}} \eta_{\text{sw}} \eta_T).$$

- For an RFID system using reflective transmission

$$P_c = \left(\frac{1}{4} |\Gamma_1 - \Gamma_2|^2 \right) \left(\frac{P_e G_c^2 G_s^2}{L_p^2} \right) (\eta_a \eta_m \eta_{\text{rec}} \eta_{\text{sw}}).$$

Uplink Energy Budget

Power received at the central controller



An SNR of 17 dB can be achieved at a distance of 5m for the PREMISS system.

Remarks

- **More detailed modeling is being considered for various building blocks of the system (on-chip antenna, rectifier, uplink transmission...)**
- **Many activities in millimeter RFID systems. However, the range is below 1 m.**
- **We consider implicit sensing schemes for energy saving in the sensor node**
 - **e.g. temperature dependency of oscillator frequency**

Conclusions

- **The PREMISS system:**
 - **60 GHz**
 - **Wireless-powered**
 - **Fully monolithic**
- **Preliminary system study shows an SNR of 17 dB can be achieved at the central controller at 5 m.**
- **Rectifier design is challenging.**

Thank you

