



Control Systems Technology

We aim to develop new methodologies for the high-tech systems of the future in a broad range of applications that are essential for our society.

To achieve this, our research spans both

world-leading applications and fundamental research

uniquely interconnected and equally important

Our core disciplines

- systems and control theory
- optimization
- systems engineering
- mechanical design / mechatronics

KPIs:

50 PhDs

85 MSc/year





CST People and subprogrammes

Bruyninckx Elfring

v Keulen

Silvas











Model-based Control, Learning Control, **Identification and Design of Motion Systems**

Cyber-Physical Systems of Systems



Robotics for Care, Cure & Agro-food





Automotive Powertrains & Smart Mobility





Process Control of Energy Systems







Lopez Martinez

Huisman



Katriniok

Krishnamoorthy de Baar

Salazar

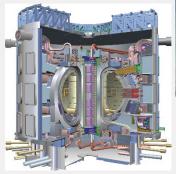
vd Molengraft Torta



Kappers

Willems

Application Areas











Vision of farming in the future: Multi-agent systems



automotive powertrains

high-tech to feed the world energy systems

Waterlocks, bridges, tunnel systems

driving and drones (UAVs)

medical (thermal, probes,..)

automated

robotics

advanced

motion &

high-tech systems

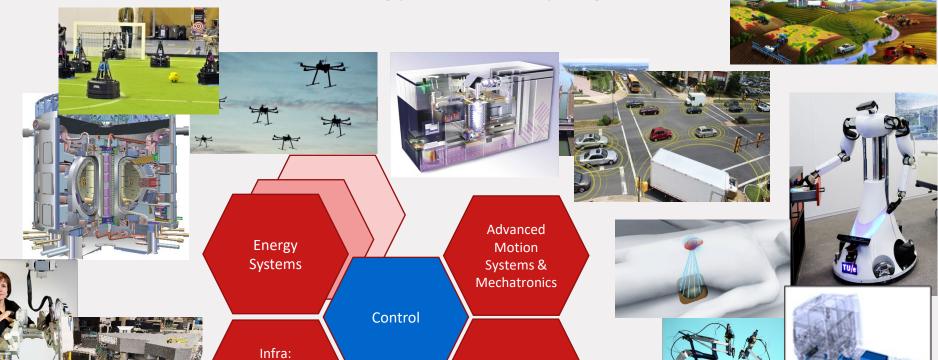




Control is the central technology in the subprogrammes

Waterlocks, Bridges,

Tunnels



Automated Driving & Powertrains

Robotics &

Drones



Vision of farming in the future: Multi-agent systems

CST Master Courses

| Code | Credits | Quartile | Title | Responsible lecturer | MW | AIES-MW | MSE-MW | ΑT | SC |
|--------|---------|----------|--|--------------------------|----|---------|--------|----|----|
| | | | | | | | | | |
| 4CM10 | 5 | Q1 | System theory for control | W.P.M.H. Heemels | S | С | S | S | С |
| 4CM00 | 5 | Q1,Q3 | Control engineering | G. Witvoet | С | С | С | S | С |
| 4CM60 | 5 | Q2 | Advanced motion control | T.A.E. Oomen | S | S | S | | S |
| 4SC010 | 2.5 | Q2 | Control and operation of tokamaks | M.R. de Baar | | | | | S |
| 4CM70 | 5 | Q2 | Integrated system design | L.F.P. Etman | S | | | | |
| 4SC000 | 5 | Q2 | Optimal control and reinforcement learning | D.J. G. Tomé Antunes | S | s | S | S | s |
| 4DM20 | 5 | Q3 | Engineering optimization | L.F.P. Etman | С | С | S | S | S |
| 4CM80 | 2.5 | Q3 | Extremum seeking control for data-based perf. optimization | T.A.C. van Keulen | S | S | | S | S |
| 4CM90 | 5 | Q3 | Opto-mechatronics | L.A. Cacace | | | | | |
| 4CM40 | 5 | Q3 | Physical and data-driven modelling | K. Tiels | S | | | S | S |
| 4CM30 | 5 | Q3 | Supervisory control | M.A. Reniers | S | S | S | S | S |
| 4AT070 | 5 | Q4 | Advanced control for future HD powertrains | F.P.T. Willems | | S | | S | S |
| 4AT030 | 5 | Q4 | Advanced full-electric and hybrid powertrain design | T. Hofman | S | | S | S | S |
| 4CM50 | 5 | Q4 | Applications of design principles | P.J.E.M. Vrancken | С | | | | |
| 4SC030 | 2.5 | Q4 | Control of magnetic instabilities in fusion plasmas | M.R. de Baar | | | | | S |
| 4SC040 | 2.5 | Q4 | Haptics - perception and technology | A.M.L. Kappers | | | | | S |
| 4CM20 | 5 | Q4 | Hybrid systems and control | W.P.M.H. Heemels | S | | S | S | S |
| 4SC070 | 5 | Q4 | Learning control | T.A.E. Oomen | | S | | | S |
| 4SC020 | 5 | Q4 | Mobile robot control | M.J.G. van de Molengraft | | S | | | S |
| | | | | | | | | | |

Programme Structure

| Year 1 | Core program | 25 EC | | |
|--------|------------------------|-------|--|--|
| | Specialization courses | 20 EC | | |
| | Free electives | 15 EC | | |
| Year 2 | Internship | 15 EC | | |
| | Graduation Project | 45 EC | | |

Year 1: Course program: In consultation with your mentor, you choose your course program for Q2-Q4. In Q3-Q4 start discussing internship (abroad/industrial/university, and scope theory/application).

Elective courses give you the chance to deepen or broaden your knowledge: 20 EC **specialization** from a list of more than 30 courses, 15 EC of **free electives** from within the total range of master courses at the TU/e (TU Delft or UTwente).

Year 2: Internship & Graduation project: This can be with your mentor or different CST scientist depending on your interests.

You start an **internship** (15 credit points) within broad area covered by CST. You follow your internship, preferably abroad, at one of the many university Systems & Control groups that are worldwide. For international students the project is often carried out at the TU/e or local industry.

The **graduation project** (45 credits). Primarily, you will gain experience in modeling, analysis, and/or design of a new control system or explore new research questions. Graduation work consists of your master project, a report/paper and a presentation. CST has numerous contacts with Dutch industry and knowledge institutes such as ASML, Océ, Philips, Shell and TNO (Netherlands organization for Applied Scientific Research).

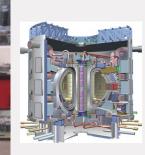
Internship and graduation project often in <u>context of PhD research</u> (possibly at/in collaboration with industry) * supervised by PhD student + one or more staff members (and industrial supervisors)



Summarizing







CST group unites

- Science and fundamental (control) theory
- Applied research & design
- Society / Spin-offs





Highest quality standards & fun!

 Two latest int. research evaluations. Excellent highest possible scores (quality, productivity, viability and relevance: 5555)















For students who are interested:

AT follow-up meeting: September 22 12:30-13:30 GEM-Z0.05

Follow-up meeting S&C 21/09/2022

CST Lab tour

11:45 – 12:55 Robotics Lab, Impuls building (Entrance on the back of Impuls, doors will be open). There will be

"Worstenbrood"/ vegatarian ©

12:55 - 13:00 Walk to the Gemini Building

13:00 - 13:30 DCT Lab Gem-z -1.13

PLEASE SIGN UP: cst sa@tue.nl

Movies/Links CST

https://www.youtube.com/watch?v=yoAoTUnkvMs&t=1s [robocup - TechUnited - 1 min]

https://www.youtube.com/watch?v=Za13vkL7Flo [robots at home competition – 4 min]

Oomen – Learning in Machines [1 min]

Maarten Steinbuch -- IFAC World Congress Plenary [49 min]

<u>Duarte Antunes – Quadcopters 1 [56 sec]</u>

Duarte Antunes - Quadcopters 2 [50 sec]

www.heemels.tue.nl

https://maartensteinbuch.com

http://www.toomen.eu

https://www.techunited.nl

https://www.linkedin.com/company/control-systems-technology-tue/

https://www.tue.nl/en/research/research-groups/control-systems-technology/

More details about our group







T: +31 (0)40 247 9111 www.tue.nl

| Buildings | MIP | Market | | MAP | MIMBER |
|--------------------|------------|--------|------------------|------------|--------|
| Alpha | D3 | 57 | Gaslab | B5 | 12 |
| Athene | C5 | 16 | Gemini | C4 | 15 |
| Atlas | B4 | 3 | Helix | C5 | 14 |
| Auditorium | B4 | 1 | Impuls | В3 | 30 |
| Aurora | С3 | 42 | Kennispoort | A5 | 2 |
| BBC | | | Koepel | F4 | |
| Reststoffencentrum | E4 | 70 | Luna | В3 | 31 |
| Cascade | D4 | 23 | Matrix | B5 | 10 |
| Catalyst | E3 | 76 | MetaForum | C4 | 5 |
| Ceres | C4 | 7 | Momentum | F4 | 83 |
| Connector | D3 | 60 | Neuron | C4 | 32 |
| Cyclotron | D5 | 24 | Qubit | D4 | 21 |
| Differ | E4 | 73 | Spectrum | D4 | 25 |
| Distruptor | E3 | 74 | Studentensport - | C2 | 49 |
| Echo | E 5 | 28 | centrum | | |
| Fenix | F4 | 87 | Traverse | C3 | 37 |
| Flux | D4 | 19 | Twinning center | F3 | 77 |
| Fontys ER | C5 | 20 | Ventur | E4 | 80 |
| Fontys S1 | D3 | 54 | Vertigo | B5 | 6 |
| Fontys S2 | D3 | 55 | Zwarte Doos | B 5 | 4 |
| Fontue S2 | D3 | 50 | | | |

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| s S2 D3 55 | | Zwarte Do | Doos | | 4 | |
|-----------------|-----------|-----------|-------------|-----------|-----------|--------|
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| artment | s | | | | | MANGER |
| ed Physics | | | | Flux | D4 | 19 |
| edical Engineer | ring | | | Gemini | C4 | 15 |
| ical Engineerin | ng and Cl | iemi | stry | Helix | C5 | 14 |
| tment of the B | uilt Envi | ronm | ent | Vertigo | 85 | |
| oven School of | Educati | on | | Traverse | C3 | 37 |
| ical Engineerin | ıg | | | Flux | D4 | 19 |
| trial Design | | | | Atlas | B4 | 3 |
| trial Engineeri | ng & Inn | ovati | on Sciences | Atlas | B4 | |
| ematics and Co | mputer | Scien | ce | MetaForum | C4 | |

Gemini C4 15

